GENETIC NEURAL NETWORKS

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ABSTRACT — This paper focuses on the training procedure of artificial neural networks for portfolio management. More specifically, it investigates a neural network -with weights derived from a genetic algorithm embedded in the training process, that automates a buy/sell/hold procedure by learning from the direction of a stock within a "diversified portfolio" (in this case a portfolio of the Dow Jones Industrial Index; hence the loose usage of the term). The binary indicators are generated using a function that observes the daily percentage changes of the index and assigns the corresponding operator if the change is a more than 5% gain, more than a 5% loss, or anything in between. Further development of the project can incorporate a diversified portfolio of securities and reallocate the portfolio weights and/or target beta and then execute the appropriate transactions or complete liquidation of the portfolio depending on its performance. While genetic algorithms are not the end-all of metaheuristic methods, the healthy skepticism that machine learning in a panacea for quantitative finance warrants a rethinking of neural networks. Embedding more traditional techniques could provide better alternatives to the sometimes unnecessarily -and even fatally, complex methods developed in the field.

KEYWORDS — Algorithms, Artificial, Evolutionary, Genetic, Liquidation, Networks, Neural, Portfolio Management, Training.

I. FEEDFORWARD NEURAL NETWORKS

A deep feedforward network is a function of the form,

$$\widehat{Y}(X) := F_{W,b}(X) = (f_{W^{(L)},b^{(L)}}^{(L)} \dots \circ f_{W^{(1)},b^{(1)}}^{(1)})(X)$$

where,

- *f*^(l)_{W^(l),b^(l)}(X) := σ^(l)(W^(l)X + b^(l)) is a semi-affine function with σ^(l) as a univariate, continuous non linear activation function such as tanh(●), sigmoid, or max(●, 0),
- $W = (W^{(1)}, ..., W^{(L)})$ are the weight matrices (which will be substituted by the optimal weights generated by the genetic algorithm described below),

•
$$b = (b^{(1)}, \dots, b^{(L)})$$
 are the offsets.



Figure 1: Structure of a feedforward network.



Figure 2: A feedforward, a recurrent and a Long-Short Term Memory (LSTM) network. Yellow indicates the input nodes, blue the hidden nodes with recurrence/memory, and red the output nodes. Source: Van Veen, F. & Leijnen, S. (2019)

II. GENETIC ALGORITHMS

A. Survival of the fittest

Genetic algorithms search for the optimal solution in a solution space. While Darwinian evolution maintains a population of specimens, genetic algorithms work through a population of candidate solutions, called individuals. The candidate solutions are evaluated and transformed into a novel generation of solutions. In a "survival of the fittest" contest, the more suitable solutions have an increased probability of being selected and passing their qualities to the next generation of candidate solutions.

B. Population

Since each individual solution is usually represented by a series of binary strings, the population of individuals can be viewed as a collection of solutions. The population represents the current population and evolves with each iteration

C. Fitness function

At each iteration of the algorithm, the individuals are evaluated using a fitness or target function, which is the function under optimization. Individuals with a higher fitness score are more likely candidates to create "off-

spring" in the next generation of solutions. Over time, the quality of the solutions improves, the fitness values increase, and the process can stop once a solution is found with a satisfactory fitness value.

D. Crossover

For the next generation, two parents are chosen from the current generation and are recombined to create children weights in a specific fashion. In this project, a quasirandom matrix multiplication between the different weights is implemented.

E. Mutation

A mutation works as a seed to refresh the population and expand the areas under search in the solution space. Mutations in this project were implemented as a multiplication with an integer drawn from a random uniform distribution.

The main advantages of genetic algorithms that make them suitable for a neural network hybrid are the following:

- Potential to find a global optimum
- Ability to handle problems with a complex mathematical definition
- Adversity to noise

III. DATA

Date	^DJI	Percent Change	Liquidate
2007-01-03	12474.519531	0.000000	0
2007-01-04	12480.690430	0.000495	0
2007-01-05	12398.009766	-0.006625	-1
2007-01-08	12423.490234	0.002055	0
2007-01-09	12416.599609	-0.000555	0
2020-01-06	28703.380859	0.002392	0
2020-01-07	28583.679688	-0.004170	0
2020-01-08	28745.089844	0.005647	1
2020-01-09	28956.900391	0.007369	1
2020-01-10	28823.769531	-0.004598	0

Figure 3: Sample data used in the training/testing process. It is worth noting that the "Liquidate" column refers to the binary operators assigned to each datapoint depending on whether the movement is favorable for the "diversified portfolio".

The data was generated using a built-in percent change function and a custom if/elif/else function that assigns the binary operators to each datapoint. The daily adjusted close price across 7 years for the Dow Jones Industrial index is also suitable for the discovery of a fundamental beta upon the expansion of the engine source code to include a real diversified portfolio of securities. However, the user is in the position to adjust the duration of the time span of their data to meet their needs.

IV. GENETIC NEURAL NETWORKS

A genetic neural network can be defined as the same function for a neural network,

$$\widehat{Y}(X) := F_{p,b}(X) = (f_{p^{(L)},b^{(L)}}^{(L)} \cdots \circ f_{p^{(1)},b^{(1)}}^{(1)})(X)$$

where,

• $f^{(l)}_{\mathcal{P}^{(l)}, b^{(l)}}(X) := \sigma^{(l)} \left(\mathcal{P}^{(l)} X + b^{(l)} \right)$ is a semi-affine function with $\sigma^{(l)}$ as a univariate, continuous non-

linear activation function such as $tanh(\bullet)$, sigmoid, or $max(\bullet, 0)$,

• $\mathscr{P} = (\mathscr{P}^{(1)}, ..., \mathscr{P}^{(L)})$ are the weight matrices (which will be substituted by the optimal weights generated by the genetic algorithm described below,

•
$$b = (b^{(1)}, \dots, b^{(L)})$$
 are the offsets.



Figure 4: Structure of a genetic neural network.

V. RESULTS AND DISCUSSION

The parameters and essential metrics of the Feedforward Neural Network construct are the following:

- 500 Epochs
- Initial Fitness Score: 0.26
- Fitness Score at the end of Epoch 500: 0.53

Epoch 1/500 77/77 [================]]	0s	3ms/step
- loss: 0.9712 - accuracy: 0.2590		
Epoch 2/500 77/77 [=======================]	0s	3ms/step
- loss: 0.9698 - accuracy: 0.2590		
Epoch 3/500 77/77 [=======================]	0s	3ms/step
- loss: 0.9685 - accuracy: 0.2590		
Epoch 4/500 77/77 [=======================]	0s	3ms/step
- loss: 0.9672 - accuracy: 0.2590		
Epoch 497/500 77/77 [================]]	0s	3ms/step
- loss: 0.7410 - accuracy: 0.5474		
Epoch 498/500 77/77 [=============]]	0s	3ms/step
- loss: 0.7410 - accuracy: 0.5474		
Epoch 499/500 77/77 [===============]]	0s	3ms/step
- loss: 0.7410 - accuracy: 0.5474		
Epoch 500/500 77/77 [================]]	0s	3ms/step
- loss: 0.7410 - accuracy: 0.5474		
Test Accuracy: 0.53		

Figure 5 Sample output of the Feedforward Neural Network.

In contrast, the following are the parameters and essential metrics of the Genetic Neural Network:

- 10 Epochs
- Initial Fitness Score: 0.52
- Fitness Score at Generation 160: 0.81

We see that the test accuracy increased by 28% within a shorter relative timespan. However, the absolute running time of the genetic algorithm was 12% higher, owing to the increased computational complexity of the genetic algorithm. The metaheuristic could be further improved with a more elaborate penalization mechanism in the mutation step (than the one currently implemented) to test for separate cases and exclude more scenarios where the mutations themselves are deemed unsuitable by the user.

```
[array([[1.4918541]], dtype=float32), array([[-
0.9948138, 0.36493468, -0.271497]], dtype=float32),
array([[-0.44647908, 0.42858624, -0.00314045], [-
0.14004254, 0.7530701, 0.5343478], [0.28062987, -
0.89855146, -0.8241141]], dtype=float32),
array([[-0.27276278, 0.20729327, -0.39682007], [
0.5404234, -0.19788313, 0.4285028], [0.10512328, -
0.47381616, -0.66573787]], dtype=float32), array([[-
0.32383364], [-1.1936888], [-1.0405163]],
dtype=float32)]
Gen 1 Test Accuracy: 0.52
```

Figure 6 Sample output of the Genetic Neural Network.

VI. NEXT STEPS

In the next steps of this project, one can create pipeline for portfolios of multiple securities to fully implement the concept of the genetic neural network. The signals could then be based on realized portfolio return and reallocate portfolio weights and/or target beta at specified time intervals (daily, weekly etc.). Finally, the algorithm can then execute the buy/hold/sell of individual securities or liquidation of the entire portfolio depending on the performance of its constituents, as the current design stands.

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VIII. REFERENCES

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IX. APPENDIX

```
"""
Automatically generated by Colaboratory.
Original file is located at:
https://colab.research.google.com/drive/13
y3WikWhCD1BNPSGeuOV_90Ua3Ww5u3
"""
```

```
# Import Packages
import random
import numpy as np
import pandas as pd
from keras.layers import Dense
from keras.models import Sequential
from sklearn.metrics import accuracy_score
from sklearn.model_selection import
train_test_split
import pandas_datareader.data as web
import matplotlib.pyplot as plt
```

```
# Genetic Neural Network class
class ENN(Sequential):
    def __init__(self, wts_sub=None):
        super().__init__()
        if wts_sub is None:
            layer1 = Dense(1,
        input_shape=(1,), activation='sigmoid')
            layer2 = Dense(3,
        activation='sigmoid')
            layer3 = Dense(3,
        activation='sigmoid')
            layer4 = Dense(3,
        activation='sigmoid')
            layer5 = Dense(1,
        activation='sigmoid')
```

```
self.add(layer1)
self.add(layer2)
self.add(layer3)
self.add(layer4)
self.add(layer5)
```

else:

```
self.add(Dense(1, input_shape=(1,), activatio
n='sigmoid', weights=[wts_sub[0],
np.zeros(1)]))
self.add(Dense(3, activation='sigmoid', weigh
ts=[wts_sub[1], np.zeros(3)]))
self.add(Dense(3, activation='sigmoid', weigh
ts=[wts_sub[2], np.zeros(3)]))
```

```
self.add(Dense(3,activation='sigmoid',weigh
ts=[wts_sub[3], np.zeros(3)]))
self.add(Dense(1,activation='sigmoid',weigh
ts=[wts_sub[4], np.zeros(1)]))
```

```
def mutation(wts_sub):
    choose = random.randint(0,
len(wts_sub)-1)
    mut = random.uniform(0, 1)
    if mut >= .5:
        wts_sub[choose] *=
random.randint(2, 5)
    else:
        pass
```

```
def cross(nn1, nn2):
    nn1_weights = []
    nn2_weights = []
    wts sub = []
```

```
for layer in nn1.layers:
nn1_weights.append(layer.get_weights()[0])
```

```
for layer in nn2.layers:
nn2_weights.append(layer.get_weights()[0])
```

```
for i in range(0, len(nn1_weights)):
    split = random.randint(0,
np.shape(nn1_weights[i])[1]-1)
```

```
prices = pd.DataFrame()
tickers = ['^DJI']
for i in tickers:
    tmp = web.DataReader(i, 'yahoo',
    prices[i] = tmp['Adj Close']
prices['Percent Change'] =
prices.pct change()
def set signal(column):
    if column['Percent Change'] < -0.0050:</pre>
        signal = -1
    elif column['Percent Change'] > 0.0050:
        signal = 1
    else:
        signal = 0
    return signal
prices['Liquidate'] =
prices.apply(set signal, axis=1)
prices = prices.replace(np.nan,0)
prices = prices.drop(['^DJI'], axis=1)
prices.reset index(inplace=True,drop=True)
# Split into independent/dependent
X = prices['Percent Change']
X = 100 * X.round(8)
X = X.astype(np.float32)
print(X.astype(np.float32))
y = prices.drop(['Percent Change'], axis=1)
#y = y.astype(np.float32)
print(y)
train test split(X, y)
networks = []
pool = []
gen = 0
for i in range(0, n):
    networks.append(ENN())
fit max = 0
wts opt = []
while fit max < .9:</pre>
    print('Generation', gen)
    for nn in networks:
```

```
nn.f propagation(X train, y train)
        pool.append(nn)
    networks.clear()
    pool = sorted(pool, key=lambda x:
x.fitness)
    pool.reverse()
    for i in range(0, len(pool)):
        if pool[i].fitness > fit max:
            fit max = pool[i].fitness
            print('Fitness Score: ',
fit max)
            wts opt = []
            for layer in pool[i].layers:
       wts opt.append(layer.get weights()[0
            print(wts opt)
    for i in range(0, 5):
        for j in range(0, 2):
            temp = cross(pool[i],
random.choice(pool))
            networks.append(temp)
portfolio enn = ENN(wts opt)
portfolio enn.train(10)
y predicted =
portfolio enn.predict(X test.values)
print('Accuracy: %.2f' %
accuracy score(y_test,
y predicted.round()))
# Feedforward neural network as a benchmark
portfolio nn = Sequential()
portfolio nn.add(Dense(1, input shape=(1,),
activation='sigmoid'))
portfolio nn.add(Dense(3,
activation='sigmoid'))
portfolio nn.add(Dense(3,
activation='sigmoid'))
portfolio nn.add(Dense(3,
activation='sigmoid'))
portfolio nn.add(Dense(1,
activation='sigmoid'))
portfolio nn.compile(optimizer='rmsprop', lo
ss='hinge', metrics=['accuracy'])
portfolio nn.fit(X train.values,
y train.values, epochs=500)
```

y_predicted =
portfolio_nn.predict(X_test.values)
y_predicted = np.around(y_predicted, 0)

print('Test Accuracy: %.2f' %
accuracy_score(y_test,
y_predicted.round()))